Giovanna Colombo
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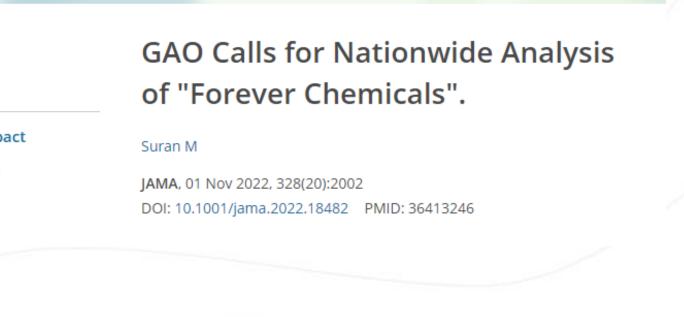


Publicación: JAMA,2022, vol. 328 num. 20 pags. 2002 Autores: Melissa Suran Artículo o capítulo: GAO Calls for Nationwide Analysis of "Forever Chemicals" ISSN: 0098-7484 DOI: 10.1001/jama.2022.18482



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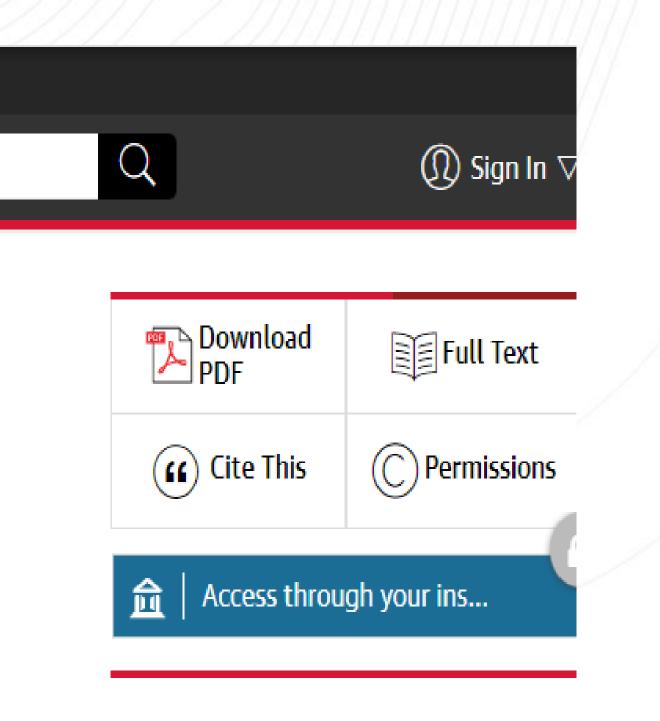
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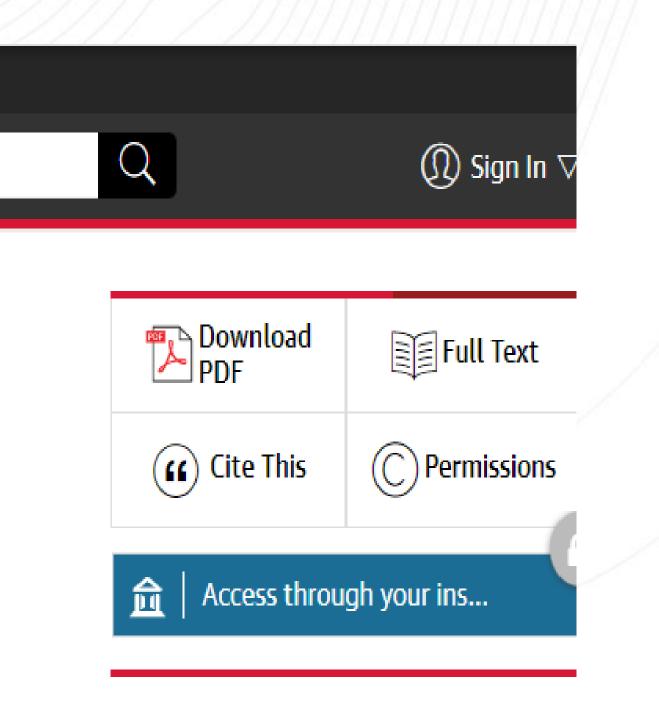
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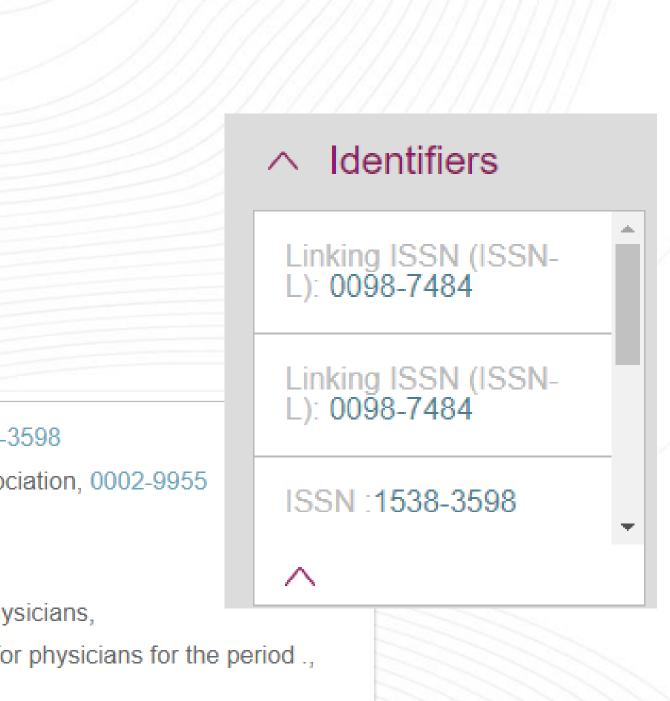
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О периодических решениях дифференциального уравнения *п*-го порядка с малым параметром

Н. Н. Боголюбов (младший) и Б. И. Садовников В настоящей статье мы будем рассматривать дифференциальное уран нение п-го порядка

 $\frac{d^n x}{dt^n} = \mu f\left(t; x, \frac{dx}{dt}, \dots, \frac{d^{n-1} x}{dt^{n-1}}; \mu\right),$ (1)в нотором f — периодическая функция t с периодом 2π, µ — малый пара-

Эти уравнения простой заменой переменных приводятся к так называе-мой стандартной форме $\frac{dx_k}{dt} = \varepsilon X(t; x, x_1, \dots, x_{n-1}; \varepsilon),$

имеющей в данном случае вид:

 $\frac{dx}{dt} = ex_1,$ $\frac{dx_1}{dt} = \epsilon x_2,$

> $\frac{dx_{n-2}}{dt} = \varepsilon x_{n-1},$

(3)

 $\frac{dx_{n-1}}{dt} = ef(t; x, ex_1, \dots, e^{n-1}x_{n-1}),$

 $\varepsilon = \mu \frac{1}{n}$.

Для построення приближенных решений уравнений в стандартной форме можно было бы воспользоваться методом усреднения, разработан-ным Н. Н. Боголобовым и Ю. А. Митропольским (1). Как известно, метод усреднения позволяет посредством замены переформе можно было бы воспол

 $x = \overline{x} + \varepsilon u_1(t, \overline{x}) + \varepsilon^2 u_2(t, \overline{x}) + \dots,$ (4) где u1 (t, x), u2 (t, x) ... - периодические функции t с периодом 2n, привес-

文献标识码: A 文 章 编 号: 1001-5965(2009)12-1483-04 Planar linkage mechanism design for bi-objective of trajectory and velocity Guo Weidong Wang Xin (School of Mechanical Engineering and Automation, Beijing University of Aeronautics and Astronautics, Beijing 100191, China) Abstract: An optimal synthesis method of planar linkage mechanism for continuous path generation was put forward, which would find the interpolation nodes of planar linkage mechanism's trajectory generation mechanism, for bi-objective of trajectory and velocity. The interpolation nodes were entrusted with the physical

meaning of the velocity by this method. The optimal synthesis model was set up based on the minimization of the error between the path-generating point in the coupler curve and the prescribed position, while the nonlincar optimization algorithm of BFGS(Broyden-Fletcher-Gddfarb-Shanno) quasi-Newton was adopted to find the global optimum solution to approximate kinematic synthesis of planar linkage. With the uniform rotation of the crank, the optimization algorithm calculated the planar linkage mechanism, satisfied the requirements of our bi-objective, and actualized the expectant target. The validity and effectiveness of the proposed method were illustrated by comparing the optimization results of four-bar mechanism and five-bar mechanism. Key words: coupler curves; path synthesis; optimal synthesis; optimization algorithm

北京航空航天大学学报

基于轨迹-速度双目标的平面连杆机构设计

郭卫东 王鑫

(北京航空航天大学 机械工程及自动化学院,北京100191) 摘 要:提出了一种在轨迹-速度双目标设计要求下优化综合连杆连续轨迹生成机

构的方法:利用机构执行末端速度运动规律寻求平面连杆轨迹生成机构插值带点,使所选取的 插值节点具有了运动速度要求的信息.基于该方法建立连续轨迹生成机构优化综合模型,以对

应轨迹点差值最小作为优化目标函数,采用 BFGS(Brovden-Fletcher-Gddfarb-Shanno) 拟牛顿非 线性优化算法优化计算机构尺寸。在设定由柄匀速转动前提下,优化计算出了符合轨迹-速度

设计要求的平面连杆机构尺寸,实现了预期的设计目标.最后比较了四杆机构和五杆机构实现

实例的优化结果,表明了该设计方法的可行性和有效性.

中图分类号: TH 112

关 鍵 词:连杆由线;轨迹综合;优化综合;优化算法

Journal of Beijing University of Aeronautics and

Vol. 35 No. 12

刚体导引机构、再现函数机构和再现轨迹机 迹与理想轨迹上对应点差值最小.文献[3]基于 预定的运动规律. 文献[1]用最小二乘法进行平 条件下的机构综合设计问题.

2009年 12月

第35卷第12期

构的设计方法仅能生成有限的某几个设定轨迹占 遗传算法实现了曲板摇杆连线轨迹生成机构的优 位,若希望所设计的机构能够生成连续轨迹或轨 化综合,这些研究都集中于如何优化实现多点轨 迹上的多个点位,就需要应用优化设计方法,使所 迹的机构设计上,而没有涉及到既有实现运动轨 设计的机构在满足一定约束条件下能最佳地逼近 迹要求,又有轨迹上运动点的速度要求的双目标

面四杆机构轨迹综合,使其最优解在结构误差上 本文将着重研究轨迹-速度双目标要求下的 满足最小二乘意义上最小,文献[2]应用拓扑算 平面连杆机构综合设计问题,给出既满足机构运 法进行平面四杆机构轨迹综合,使其优化生成轨 动轨迹要求,又同时满足轨速上运动点的速度要

收稿日期: 2008-11-28 作者简介: 郭卫东(1962 -), 男, 黑龙江拜泉人, 教授, guowd@ buaa. edu. cn.



During COVID And Beyond

日本金属学会誌 第 70 巻 第 8 号(2006)646-649

La-Ni 水素吸蔵合金と Sm-Fe 磁歪合金をポリイミド 薄板に両面蒸着した三層構造複合素子の運動歪

及川 奨1.* 增田進吾1.* 松村義人² 西義武1.2

「東海人学人学院工学研究科金属材料工学専攻 *東海大学進合大学院理工学研究科総合理工学専攻

J. Japan Inst. Metals, Vol. 70, No. 8 (2006), pp. 646-649 © 2006 The Japan Institute of Metals

Motion Strain of Three-Layered Composite Device of Polymer Film Coated with Magnetostrictive SmFe3.6 Hydrogen Absorbed LaNi5 Alloys

Tsutomu Oikawa^{1,*}, Shingo Masuda^{1,*}, Yoshihito Matsumura² and Yoshitake Nishi^{1,2} Department of Metallurgical Engineering, Graduate School of Engineering, Tokai University, Hiratsuka 259-1292

Unified Graduate School of Science and Engineering, Tokai University, Hiratsuka 259-1292

three-layered composite mover device constructed with both hydrogen storage La-Ni and compressive magnetor Sm-Fe alloy thin films on each side surface of polyinide substrate has been prepared by using a flash vacuum evaporation and a direct current magneton sputtering, respectively. When the motion strain is about -750 ppm at ± 400 kA/m of magnetic field before hydrogenation, it is about -1150 ppm after hydrogenation. The hydrogenation of the La-Ni alloy film in the three-layered composite mover device enhances the magnetoricitic.

(Received April 28, 2006; Accepted June 16, 2006)

Keywords: samarium-iron alloy, lanthanum-nickel alloy, layer composite, mover film, flash vacuum evaporation, direct current mag netron sputtering

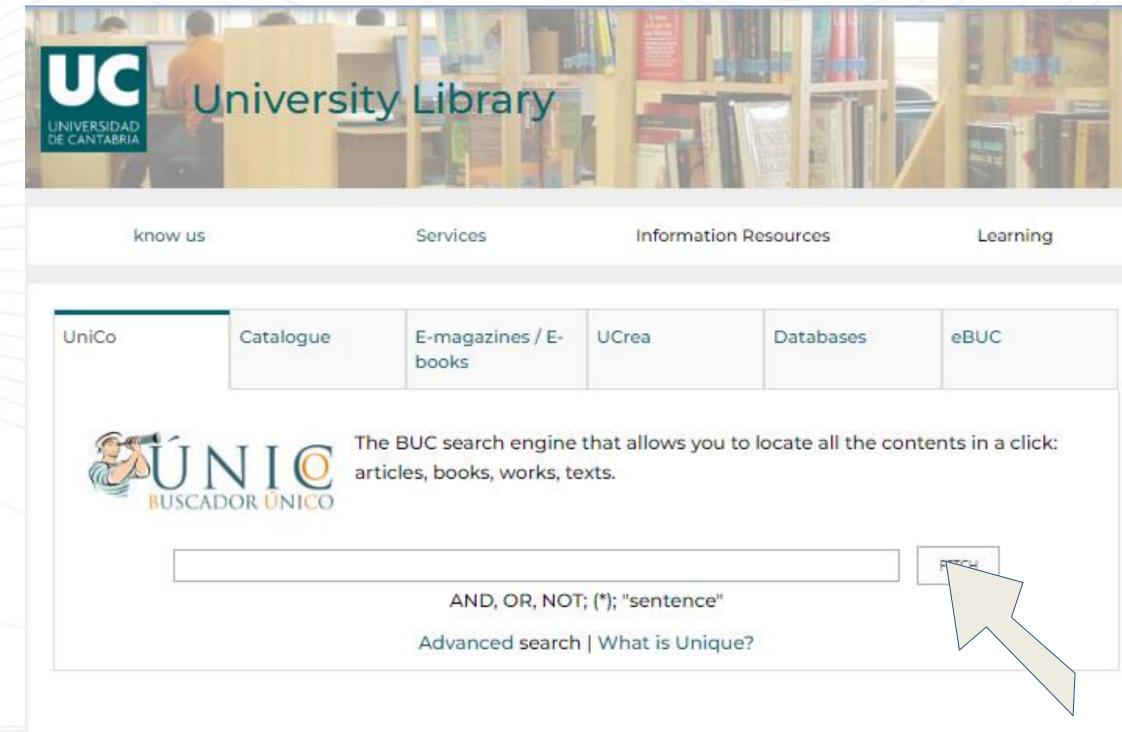
1. 緒 言

近年,希土類(R)-鉄系(Fe)化合物のうち Laves 相を有す る RFe₂ 金属間化合物系合金結晶が,1000 ppm 以上もの大 物の中には、目的相となる RFe2 までに包晶反応を 2 回も経 吸藏特性を示すため¹²⁾,水素圧力により制御が容易である。 る場合があり、均質組成の試料を得ることは困難なものがあ る²⁾. しかし,スパッタ法で作製した Sm-Fe 薄膜は均質組 成のアモルファス構造となる場合がある.アモルファスは結 を課題としてきた.一方,磁歪材料が木素吸蔵によって、変 なる面内磁化膜であることから低磁場で高い磁歪特性を示 い.しかしながら、使用環境で長時間、水素化によって磁歪 駆動力の1つとして、水素吸蔵合金海膜の水素吸蔵による 制御弁などの素子の実現が期待できる。そこで本研究では、 エータに関して、我々はLaNi, 合金薄膜を用いて様々な研 素子の開発を行い、検討を行った、すなわち、Sm-Fe 超磁 完も行っている⁶⁴⁾, 一般にバルク材の水素吸蔵合金は水素
至合金薄膜と La-Ni 水素吸蔵合金薄膜をそれぞれポリイミ

*東海大学大学院生(Graduate Student, Tokai University)

際化し、格子欠陥を大量に導入して結晶構造が乱れた組織を 形成することにより、水素吸蔵・放出時の膨張により試料中 に導入される内部応力の増大を防ぎ、微粉化が防止され る^{10,11)}. さらに, La-Ni 合金薄膜の場合は, 水素圧力に対し てのブラトー領域が観察されない場合のあることが報告され きな磁歪を示し、中でも SmFe2 合金結晶は巨大な圧縮磁歪 ている¹²⁾、つまり、アモルファスに類似した腰構造を有す を有することが広く知られている¹¹.しかし、R-Fe 系化合 る LaNi, 合金薄膜は、水素圧力に対して線形性の高い水素 以上のことから、これまでに本研究グループでは、上記の 特性を利用し、体積膨張・収縮を運動力として利用すること Sm-Fe 合金のアモルファス薄膜は磁化容易輪が面内方向と 複合化し、運動素子として利用する試みは全く行われていな す²⁰. これらのことから、我々は運動機能材料として超磁歪 材料が変質しなければ、新エネルギーシステムの重要な要素 材料の基礎研究を行っている3-5),一方で、運動機能材料の 技術となりえる.さらに、水素気流濃度、流量検出器、自己 体積膨張に伴う発生応力を利用したユニモルフ構造アクチュ 水素吸蔵合金と超磁歪材料の複合化を試み、全く新しい運動 を吸蔵し容易に微粉化を引き起こす。しかし、この合金を薄 ド基板の片面とその反対面上に形成した三層構造の複合薄膜 運動素子が大きな運動歪を示したので報告する。

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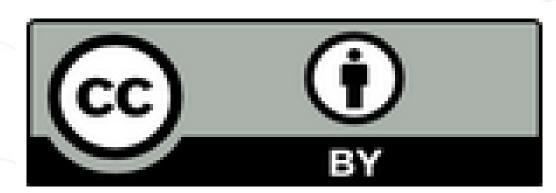
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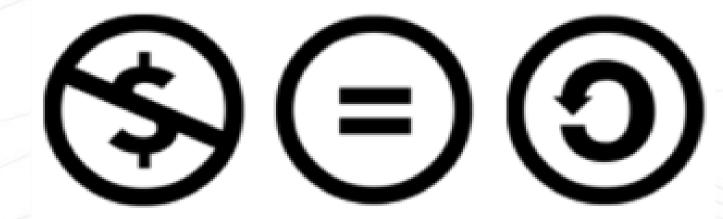


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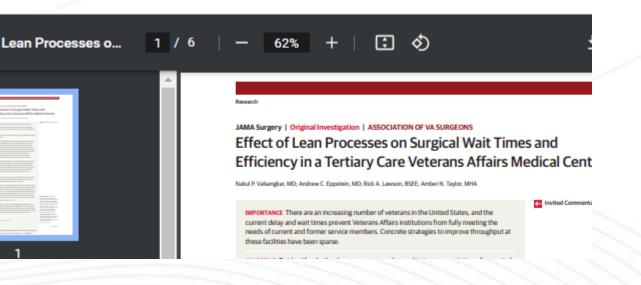
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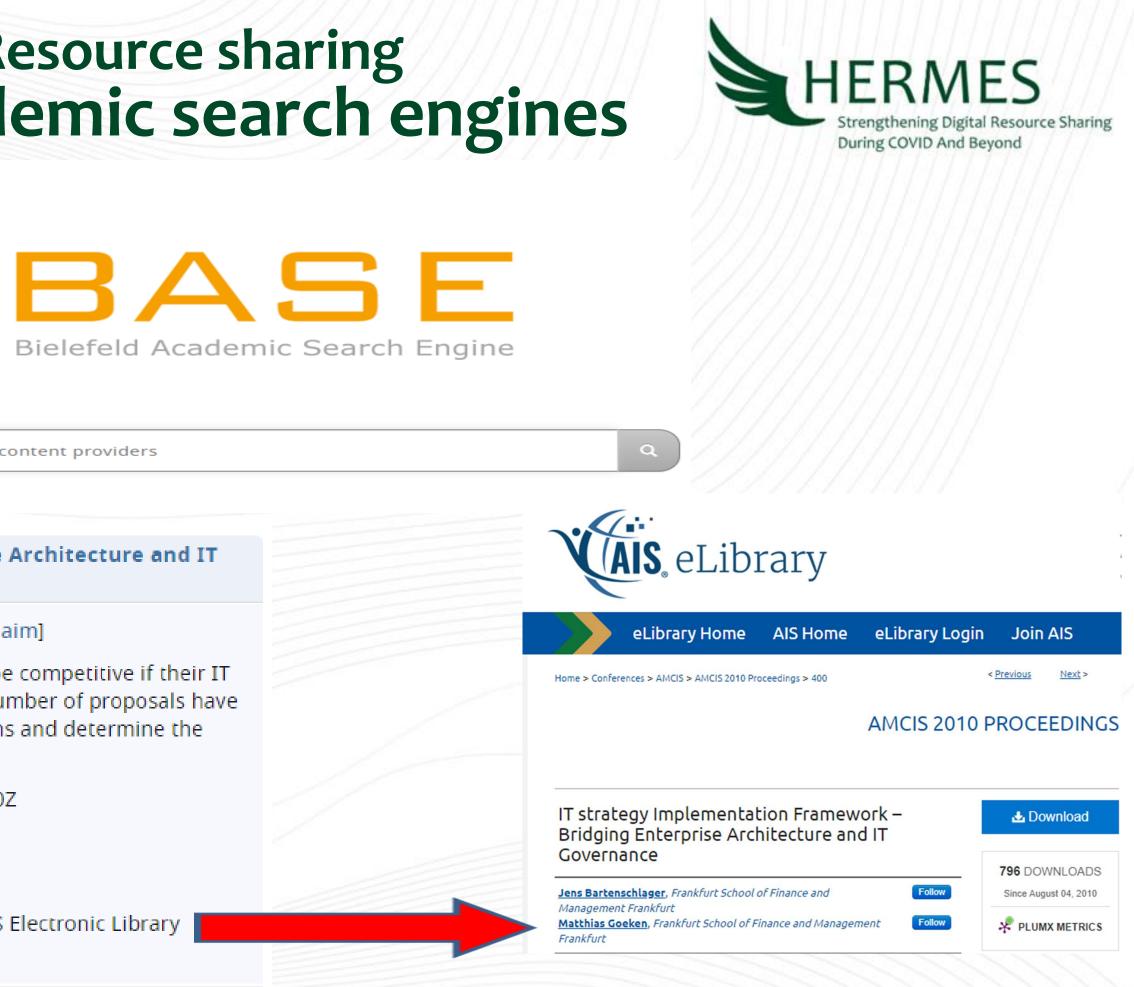
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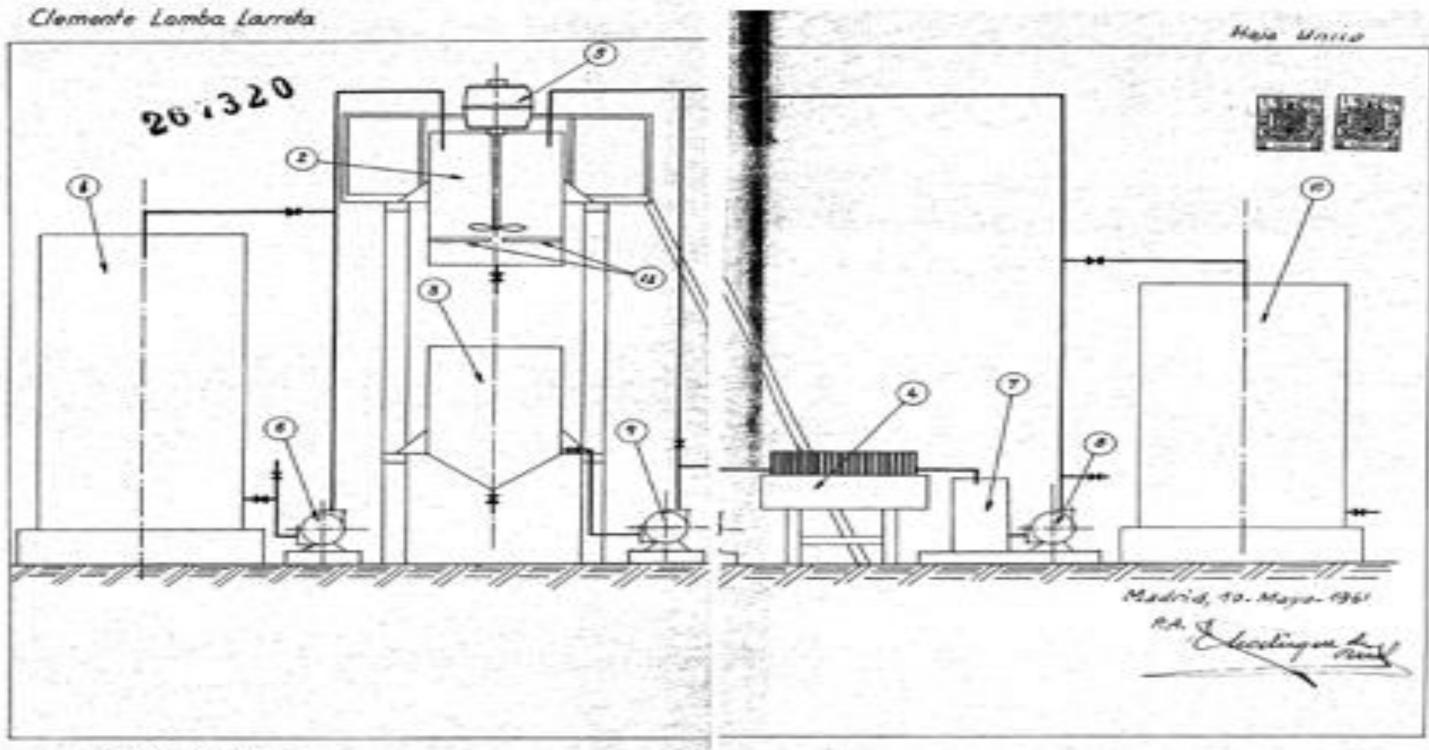


Standards



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Instruments for effective Resource sharing Where to find help?

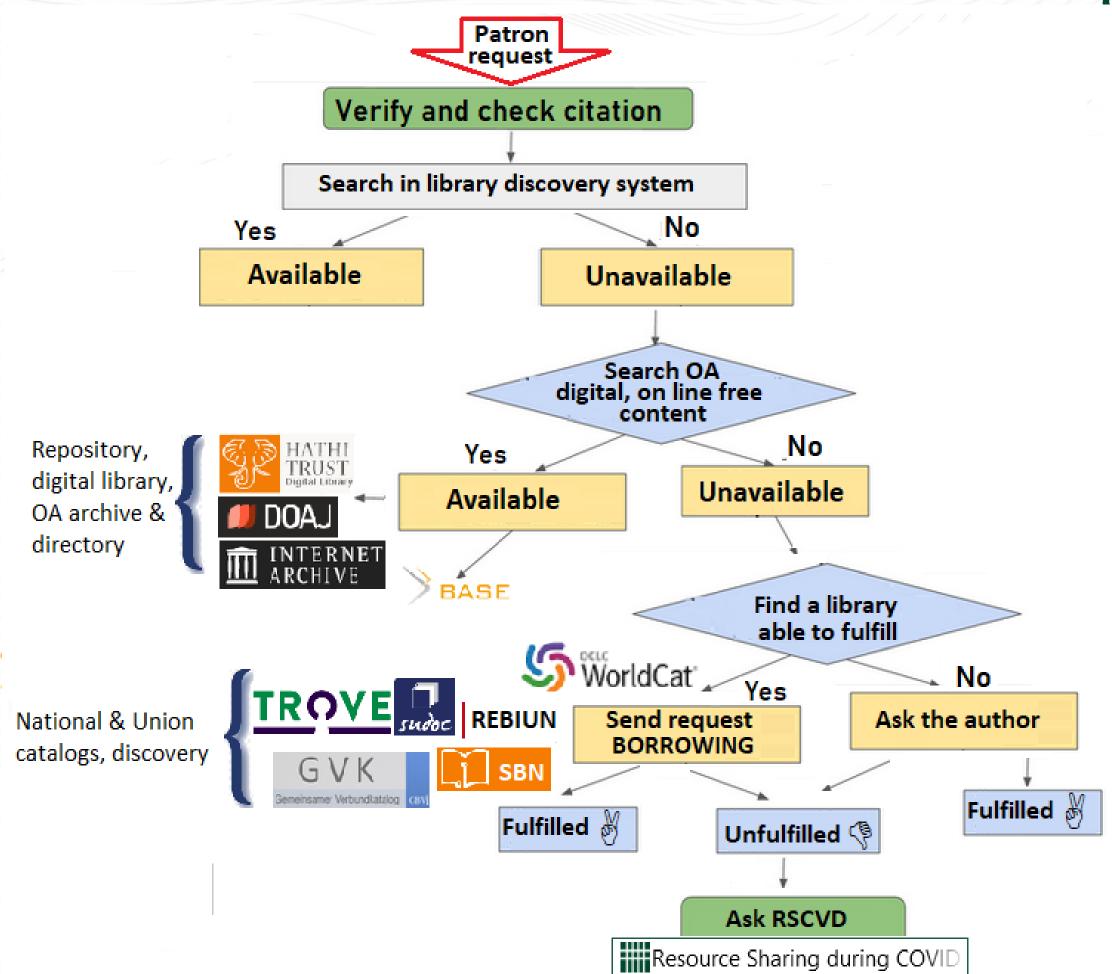
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During COVID And Beyond





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